

Chapter 6 Basic Function Instruction

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Basic Function Instruction

T	TIMER	T
Symbol		<u>Operand</u>

Ladder symbol

Time control—EN — TB — Tn — PV — TUP — Time -UP(FO0)

Tn: Timer Number.
PV: Preset value of the timer.

TB: Time Base (0.01S, 0.1S, 1S)

Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	SR	ROR	DR	K
	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3840 R3903	R3904 R3967	R3968 R4167	R5000 R8071	D0 D4095	0 32767
Tn					○								
PV	○	○	○	○	○	○	○	○	○	○	○	○	○

- The total number of timers is 256 (T0~T255) with three different time bases, 0.01S, 0.1S and 1S. The default number and allocation of timers is shown as below (Can be adjusted according to user's actual requirements by the "Configuration" function):

T0~T49 : 0.01S timer (default as 0.00~327.67S) .

T50~T199 : 0.1S timer (default as 0.0~3276.7S) .

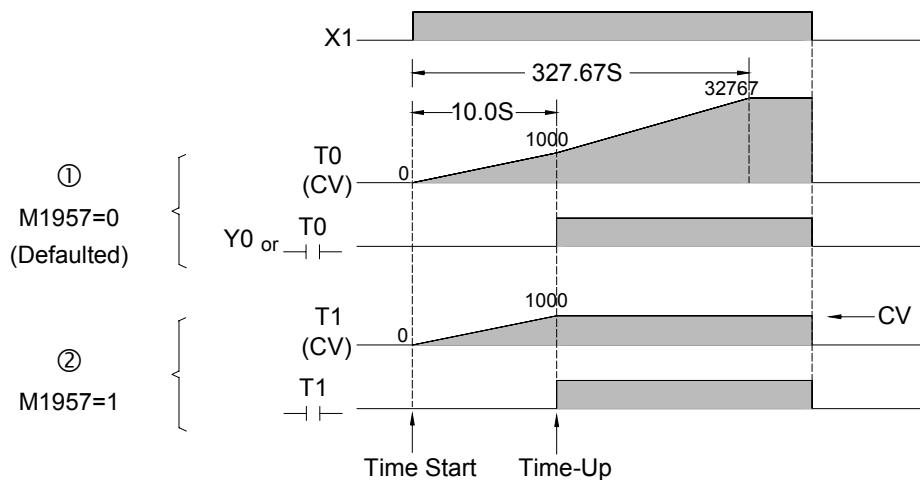
T200~T255 : 1S timer (default as 0~32767S) .

- FBs-PLC programming tool will lookup the timer's time base automatically according to the "Memory Configuration" after the timer number is keyed in. Timer's time = Time base x Preset value. In the example 1 below, the time base T0 = 0.01S and the PV value = 1000, therefore the T0 timer's time = 0.01S x 1000 = 10.00S.
- If PV is a register, then Timer's time = Time base x register content. Therefore, you only need to change the register content to change the timer's time. Please refer to Example 2.
- * The maximum error of a timer is a time base plus a scan time. In order to reduce the timing error in the application, please use the timer with a smaller time base.

Description	
<ul style="list-style-type: none"> When the time control "EN" is 1, the timer will start timing (the current value will accumulate from 0) until "Time Up" (i.e. CV\geqPV), then the Tn contact and TUP (FO0) will change to 1. As long as the timer control "EN" input is kept as 1, even the CV of Tn has reached or exceeded the PV, the CV of the timer will continue accumulating (with M1957 = 0) until it reaches the maximum limit (32767). The Tn contact status and flag will remain as 1 when CV\geqPV, unless the "EN" input is 0. When "EN" input is 0, the CV of Tn will be reset to 0 immediately and the Tn contact and "Time Up" flag TUP will also change to 0 (please refer to the diagram ① below). If the FBs-PLC OS version is higher than V3.0 (inclusive), the M1957 can be set to 1 so the CV will not accumulate further after "Time Up" and stops at the PV value. The default value of the M1957 is 0, therefore the status of M1957 can be set before executing any timer instruction in the program to individually set the timer CV to continue accumulating or stop at the PV after "Time Up" (please refer to the diagram ② below). 	

T	TIMER	T
Example 1	Constant preset value	

Ladder diagram	Key operations	Mnemonic code
<p>An example of taking "Time-Up" signal directly from FO0.</p>		ORG X 1 T0 PV: 1000 F0 0 OUT Y 0 ORG SHORT SET M 1957 ORG X 1 T1 PV: 1000



Example 2	Variable PV
<p>The preset value (PV) shown in example 1 is a constant which is equal to 1000. This value is fixed and can not be changed once programmed. In many circumstances, the preset time of the timers needs to be varied while PLC running. In order to change the preset time of a timer, can first use a register as the PV operand (R or WX, WY...) and then the preset time can be varied by changing the register content. As shown in this example, if set R0 to 100, then T becomes a 10S Timer, and hence if set R0 to 200, then T becomes a 20S Timer.</p>	

Basic Function Instruction

T	TIMER	T
Ladder diagram	Key operations	Mnemonic code
<p>An example of applying the "time-up" status by using the T50 contact.</p>		ORG X 1 T 50 PV: R 0 ORG T 50 OUT Y 0
<p>① When $R0=100 \Rightarrow Y0$ at 10.0S</p> <p>② When $R0=200 \Rightarrow Y0$ at 20.0S</p> <p>Time Start ① Time-Up ② Time-Up</p>		

Remark: If the preset value of the timer is equal to 0, then the timer's contact status and FO0 (TUP) become 1 ("EN" input must be at 1) immediately after the PLC finishes its first scan because "Time-Up" has occurred. (TUP) stays at 1 until "EN" input changes to 0.

C	COUNTER (16-Bit: C0~C199 · 32-Bit: C200~C255)	C																																																						
Symbol	Ladder symbol	Operand																																																						
		<p>Cn: The Counter number PV: Preset value</p>																																																						
		<table border="1"> <thead> <tr> <th>Range</th><th>WX</th><th>WY</th><th>WM</th><th>WS</th><th>TMR</th><th>CTR</th><th>HR</th><th>IR</th><th>OR</th><th>SR</th><th>ROR</th><th>DR</th><th>K</th></tr> </thead> <tbody> <tr> <td>Operand</td><td>WX0 WX240</td><td>WY0 WY240</td><td>WM0 WM1896</td><td>WS0 WS984</td><td>T0 T255</td><td>C0 C255</td><td>R0 R3839</td><td>R3840 R3903</td><td>R3904 R3967</td><td>R3968 R4167</td><td>R5000 R8071</td><td>D0 D4095</td><td>0 2147483647</td></tr> <tr> <td>Cn</td><td></td><td></td><td></td><td></td><td></td><td>○</td><td></td><td></td><td></td><td></td><td></td><td></td></tr> <tr> <td>PV</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td></tr> </tbody> </table>	Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	SR	ROR	DR	K	Operand	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3840 R3903	R3904 R3967	R3968 R4167	R5000 R8071	D0 D4095	0 2147483647	Cn						○							PV	○	○	○	○	○	○	○	○	○	○	○	○
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PV	○	○	○	○	○	○	○	○	○	○	○	○																																												
Description	<ul style="list-style-type: none"> There are total 200 16-Bit counters (C0~C199). The range of preset value is between 0~32767. C0~C139 are Retentive Counters and the CV value will be retained when the PLC turns on or RUN again after a power failure or a PLC STOP. For Non Retentive Counters, if a power failure or PLC STOP occurs, the CV value will be reset to 0 when the PLC turns on or RUN again. There are total 56 32-Bit counters (C200~C255). The range of the preset value is between 0~2147483647. C200~C239 are Retentive Counters and C240~C255 are Non Retentive Counters. The default number and assignment of the counters are shown below, if necessary can use the "CONFIGURATION" function to change the settings. To insure the proper counting, the sustain time of input status of CLK should greater than 1 scan time. The max. counting frequency with this instruction can only up to 20Hz, for higher frequency please use the high-speed soft/hardware counter. 																																																							
	<ul style="list-style-type: none"> When "CLR" is at 1, all of the contact Cn, FO0 (CUP), and CV value of the counter CV are cleared to 0 and the counter stops counting. When "CLR" is at 0, the counter is allowed to count up. The Counter counts up every time the clock "CK ↑" changes from 0 to 1 (adds 1 to the CV) until the cumulative current value is equal to or greater than the preset value (CV>=PV), the counter "Count-Up" and the contact status of the counter Cn and FO0 (CUP) changes to 1. If the input status of clock continues to change, even the cumulative current value is equal and greater than the preset value, the CV value will still accumulate until it reaches the up limit at 32767 or 2147483647. The contact Cn and FO0 (CUP) stay at 1 as long as CV>=PV unless the "CLR" input is set to 1. (please refer the diagram ① below) . If the FBs-PLC OS version is higher than V3.0 (inclusive), the M1973 can set to 1 so the CV will not accumulate further after "Count Up" and stops at the PV. M1973 default value is 0, therefore the status of M1973 can be set before executing any counter instruction in the program to individually set the counter CV to continue accumulating or stops at the PV after "Count Up" (please refer to the diagram ② below). 																																																							

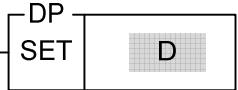
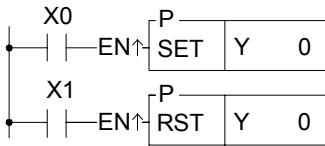
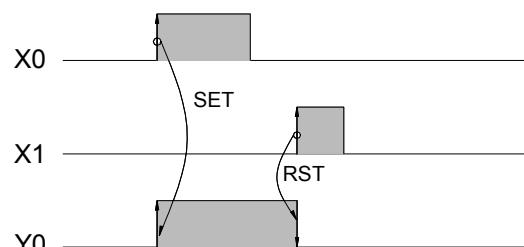
Basic Function Instruction

C	COUNTER (16-Bit: C0~C199, 32-bit: C200~C255)	C
Example 1	16-Bit Fixed Counter	
Ladder diagram	Key operations	Mnemonic code
<p>An example of applying the “Count-Up” status by using FO0 directly.</p>		ORG SHORT RST M 1973 ORG X 0 LD X 1 C 1 PV: 5 FO 0 OUT Y 1 ORG SHORT SET M 1973 ORG X 0 LD X 1 C 2 PV: 5
<p>① M1973=0 (Defaulted)</p> <p>② M1973=1</p> <p>Count Start</p> <p>Count-Up</p>		
Example 2	32-Bit counter with variable preset value	
<p>Like a timer, if the PV of a counter is changed to a register (such as R, D, and so on), the counter will use the register contents as the counting PV. Therefore, only need to change the register contents to change the PV of the counter while PLC is running. Below is an example of a 32-bit counter that uses the data register R0 as the PV (in fact it is the 32-bit PV formed by R1 and R0).</p>		

C	COUNTER (16-Bit: C0~C199, 32-Bit: C200~C255)	C
Ladder diagram	Key operations	Mnemonic code
<p>An example of applying the "time-up" status by using the C200 contact.</p>		ORG X 0 LD X 1 C200 PV: R 0 ORG C 200 OUT Y 1
<p>① When R0=4 \Rightarrow Y1 4 times</p> <p>② When R0=9 \Rightarrow Y1 9 times</p>		

Remark: If the preset value of the counter is 0 and "CLR" input also at 0, then the Cn contact status and F00 (CUP) becomes 1 immediately after the PLC finishes its first scan because the "Count-Up" has occurred. It will stay at 1 regardless how the CV value varies until "CLR" input changes to 1.

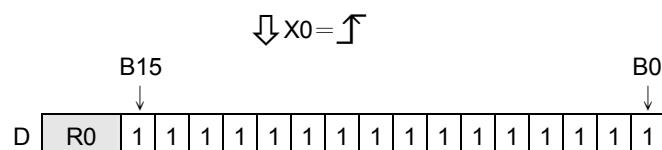
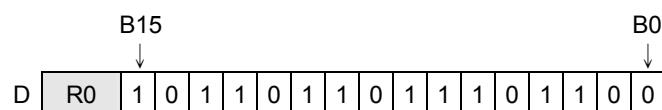
Basic Function Instruction

SET DP	SET (Set coil or all the bits of register to 1)												SET DP																																												
Symbol													Symbol																																												
	<u>Ladder symbol</u> 												<u>Operand</u>																																												
	D: destination to be set (the number of a coil or a register)																																																								
<table border="1"> <thead> <tr> <th>Range</th><th>Y</th><th>M</th><th>SM</th><th>S</th><th>WY</th><th>WM</th><th>WS</th><th>TMR</th><th>CTR</th><th>HR</th><th>OR</th><th>SR</th><th>ROR</th><th>DR</th></tr> </thead> <tbody> <tr> <td>Oper- and</td><td>Y0 Y255</td><td>M0 M1911</td><td>M1912 M2001</td><td>S0 S999</td><td>WY0 WY240</td><td>WM0 WM1896</td><td>WS0 WS984</td><td>T0 T255</td><td>C0 C255</td><td>R0 R3839</td><td>R3904 R3967</td><td>R3968 R4167</td><td>R5000 R8071</td><td>D0 D4095</td></tr> <tr> <td>D</td><td>○</td><td>○</td><td>○*</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○</td><td>○*</td><td>○*</td><td>○</td></tr> </tbody> </table>													Range	Y	M	SM	S	WY	WM	WS	TMR	CTR	HR	OR	SR	ROR	DR	Oper- and	Y0 Y255	M0 M1911	M1912 M2001	S0 S999	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3904 R3967	R3968 R4167	R5000 R8071	D0 D4095	D	○	○	○*	○	○	○	○	○	○	○	○	○*	○*	○
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D	○	○	○*	○	○	○	○	○	○	○	○	○*	○*	○																																											
Description	<ul style="list-style-type: none"> When the set control "EN" =1 or "EN ↑" (P instruction) is from 0 to 1, sets the bit of a coil or all bits of a register to 1. 																																																								
Example 1	Single Coil Set																																																								
Ladder Diagram				Key Operations				Mnemonic Codes																																																	
								ORG X 0 SET P Y 0 ORG X 1 RST P Y 0																																																	
																																																									

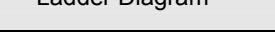
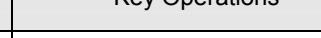
Basic Function Instruction

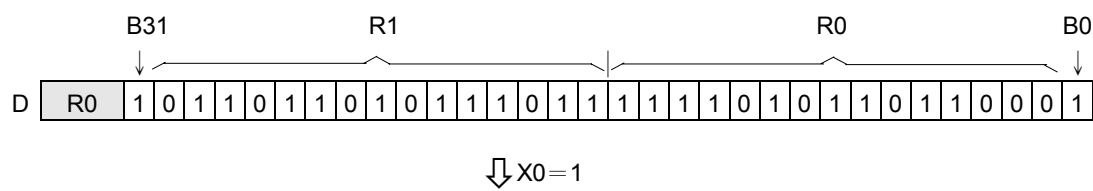
SET D P	SET (Set coil or all the bits of register to 1)	SET D P
Example 2	Set 16-Bit Register	

Ladder Diagram	Key Operations	Mnemonic Codes
		ORG X 0 SET P R 0

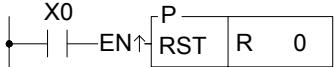
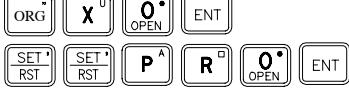
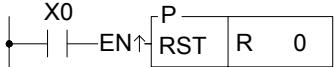
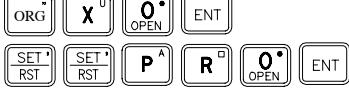
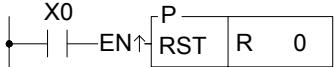
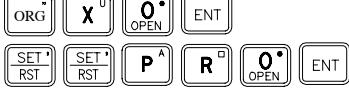


Example 3 32-Bit Register Set

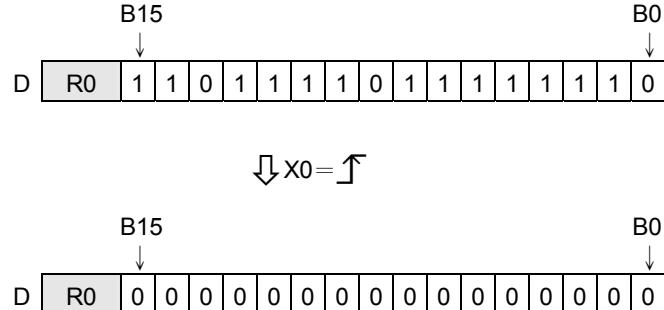
Ladder Diagram	Key Operations	Mnemonic Codes
		ORG X 0 SET D R 0



Basic Function Instruction

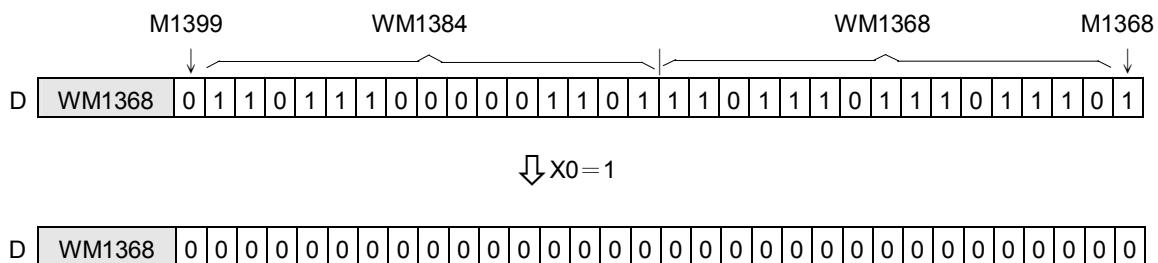
RST DP	RESET (Reset the coil or the register to 0)												RST DP																																													
Symbol													Operand																																													
<u>Ladder symbol</u>																																																										
													D: Destination to be reset (the number of a coil or a register)																																													
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Description																																																										
<ul style="list-style-type: none"> When the reset control "EN" =1 or "EN ↑" (P instruction) from 0 to 1, resets the coil or register to 0. 																																																										
Example 1	Single Coil Reset																																																									
<p>Please refer to example 1 for the SET instruction shown in page 6-8.</p>																																																										
Example 2	16-Bit Register Reset																																																									
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Ladder Diagram	Key Operations	Mnemonic Codes																																																								
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RST DP	RESET (Reset the coil or register to 0)	RST DP
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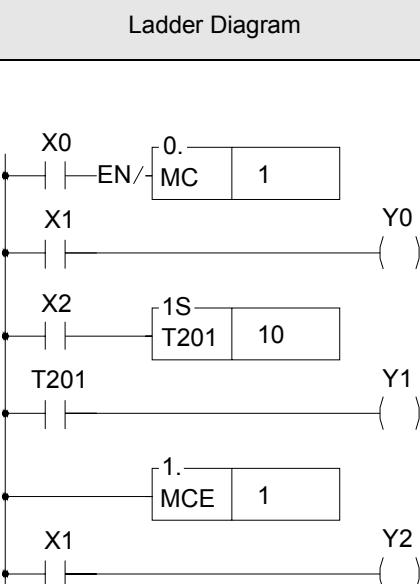
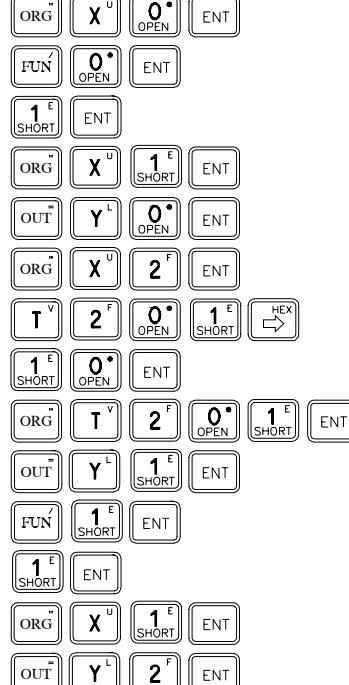
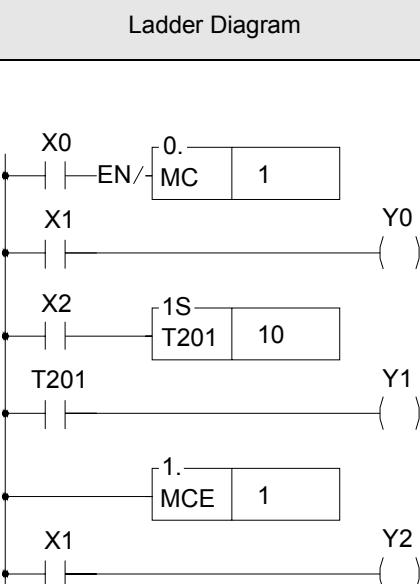
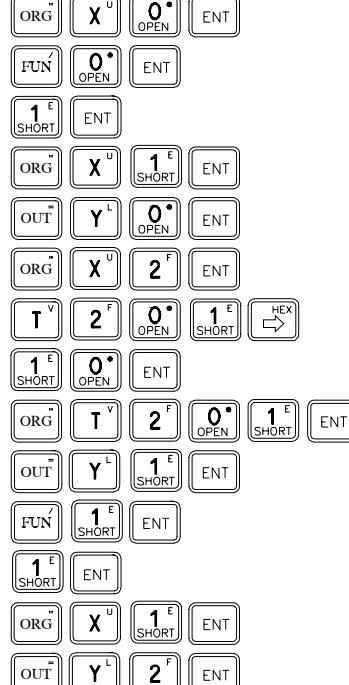
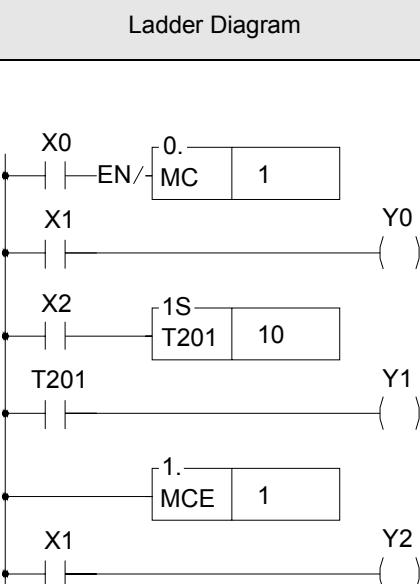
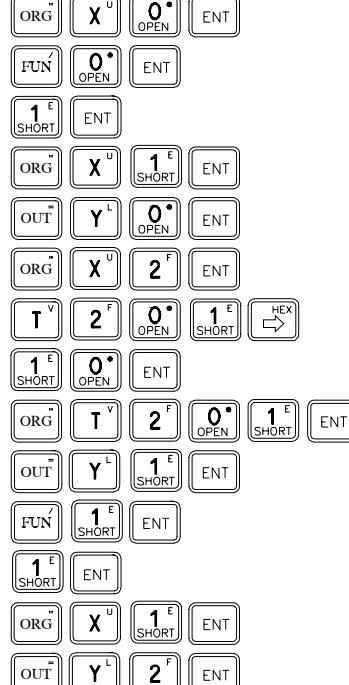


Example 3 32-Bit Register Reset

Ladder Diagram	Key Operations	Mnemonic Codes
		ORG X 0 RST D WM1368



Basic Function Instruction

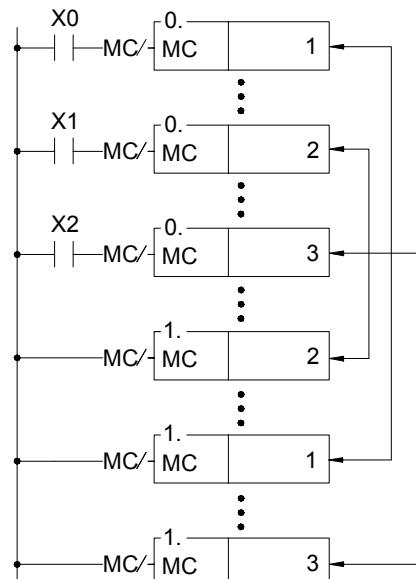
FUN 0 MC	MATER CONTROL LOOP START	FUN 0 MC						
Symbol	Ladder symbol 	Operand N: Master Control Loop number (N=0~127) the number N cannot be used repeatedly.						
Description	<ul style="list-style-type: none"> There are a total of 128 MC loops (N=0~127). Every Master Control Start instruction, MC N, must correspond to a Master Control End instruction, MCE N, which has the same loop number as MC N. They must always be used in pairs and you should also make sure that the MCE N instruction is after the MC N instruction. When the Master Control input "EN/" is 1, then this MC N instruction will not be executed, as it does not exist. When the Master Control input "EN/" is 0, the master control loop is active, the area between the MC N and MCE N is called the Master Control active loop area. All the status of OUT coils or Timers within Master Control active loop area will be cleared to 0. Other instructions will not be executed. 							
Example	<table border="1"> <thead> <tr> <th>Ladder Diagram</th><th>Key Operations</th><th>Mnemonic Codes</th></tr> </thead> <tbody> <tr> <td>  </td><td>  </td><td> ORG X 0 FUN 0 ORG X 1 OUT Y 0 ORG X 2 T201 PV : 10 ORG T 201 OUT Y 1 FUN 1 ORG X 1 OUT Y 2 </td></tr> </tbody> </table>		Ladder Diagram	Key Operations	Mnemonic Codes			ORG X 0 FUN 0 ORG X 1 OUT Y 0 ORG X 2 T201 PV : 10 ORG T 201 OUT Y 1 FUN 1 ORG X 1 OUT Y 2
Ladder Diagram	Key Operations	Mnemonic Codes						
		ORG X 0 FUN 0 ORG X 1 OUT Y 0 ORG X 2 T201 PV : 10 ORG T 201 OUT Y 1 FUN 1 ORG X 1 OUT Y 2						

FUN 0 MC	MATER CONTROL LOOP START	FUN 0 MC
	<p>Timing diagram illustrating the MATER CONTROL LOOP START function. The diagram shows the timing of inputs X0, X1, X2 and outputs Y0, Y1, Y2. Input X0 starts at time 0 and continues until time 10. Input X1 starts at time 0 and continues until time 10. Input X2 starts at time 0 and continues until time 10. Output Y0 starts at time 0 and continues until time 10. Output Y1 starts at time 10 and continues until time 10. Output Y2 starts at time 10 and continues until time 10. A 10-second delay is indicated between the start of X0 and the start of Y1.</p>	

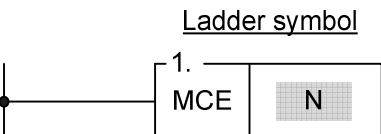
Remark1:MC/MCE instructions can be used in nesting or interleaving as shown to the right:

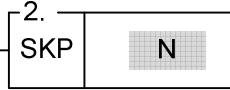
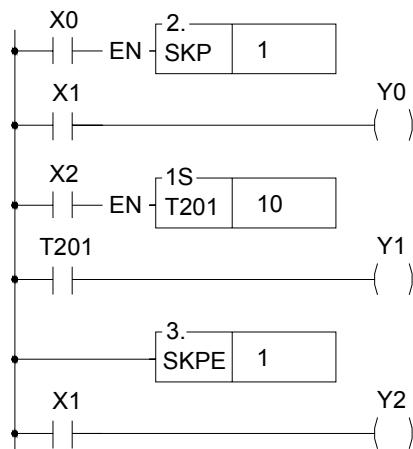
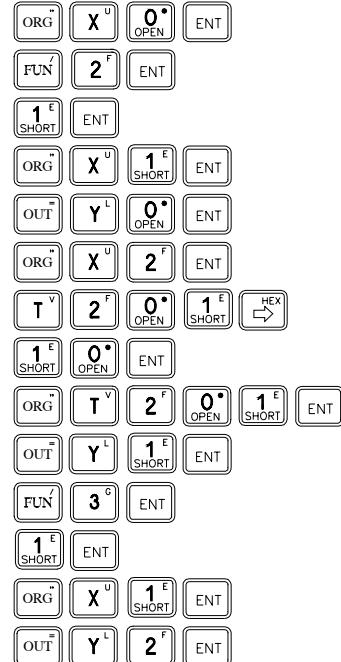
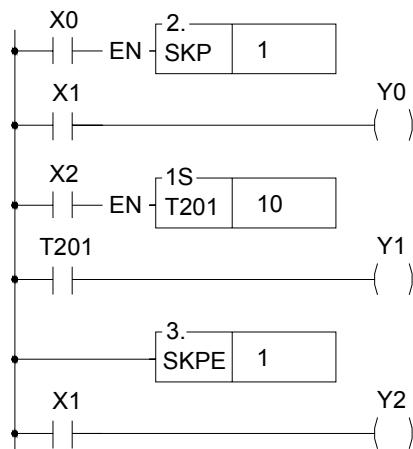
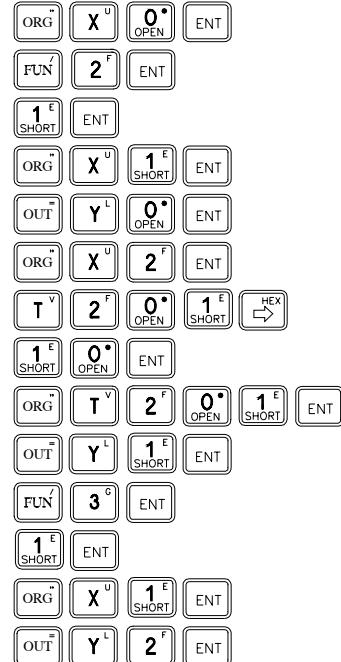
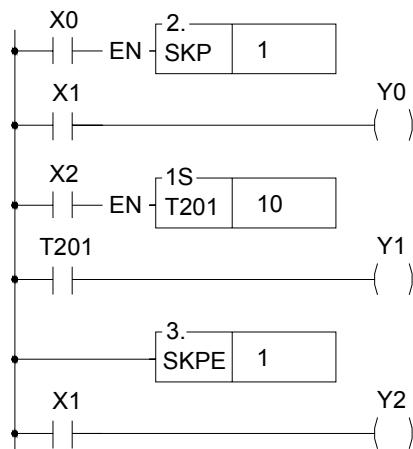
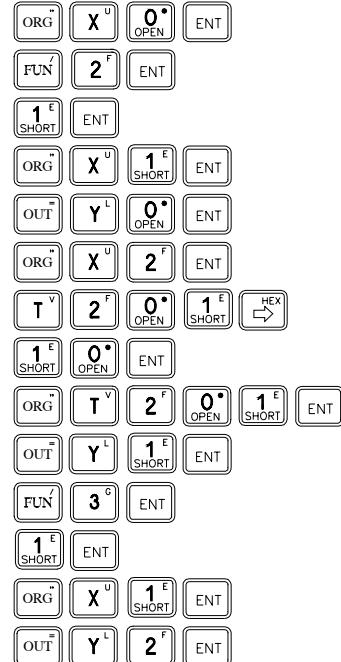
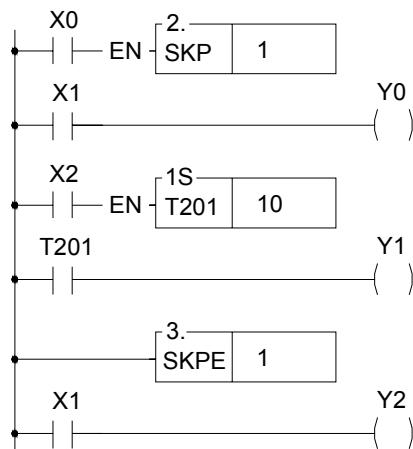
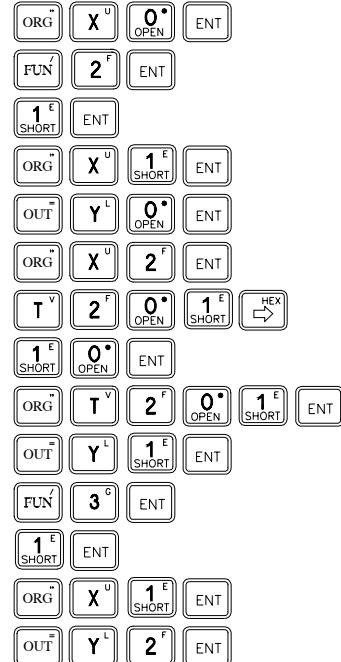
Remark2: • When M1918=0 and the master input changes from 0→1, and if pulse type function instructions exist in the master control loop, then these instructions will have a chance to be executed only once (when the first time the master control input changes from 0→1). Afterwards, no matter how many times the master control input changes from 0→1, the pulse type function instructions will not be executed again.

- When M1918=1 and the master control input changes from 0→1, and if pulse type function instructions exist in the master control loop, then each time the master control input changes from 0→1 the pulse type function instructions in the master control loop will be executed as long as the action conditions are satisfied.
- When a counting instruction exists in the master control loop, set M1918 to 0 can avoid counting error.
- When the pulse type function instructions in the master control loop must act upon the 0→1 input change by the master control, the flag M1918 should be set to 1.

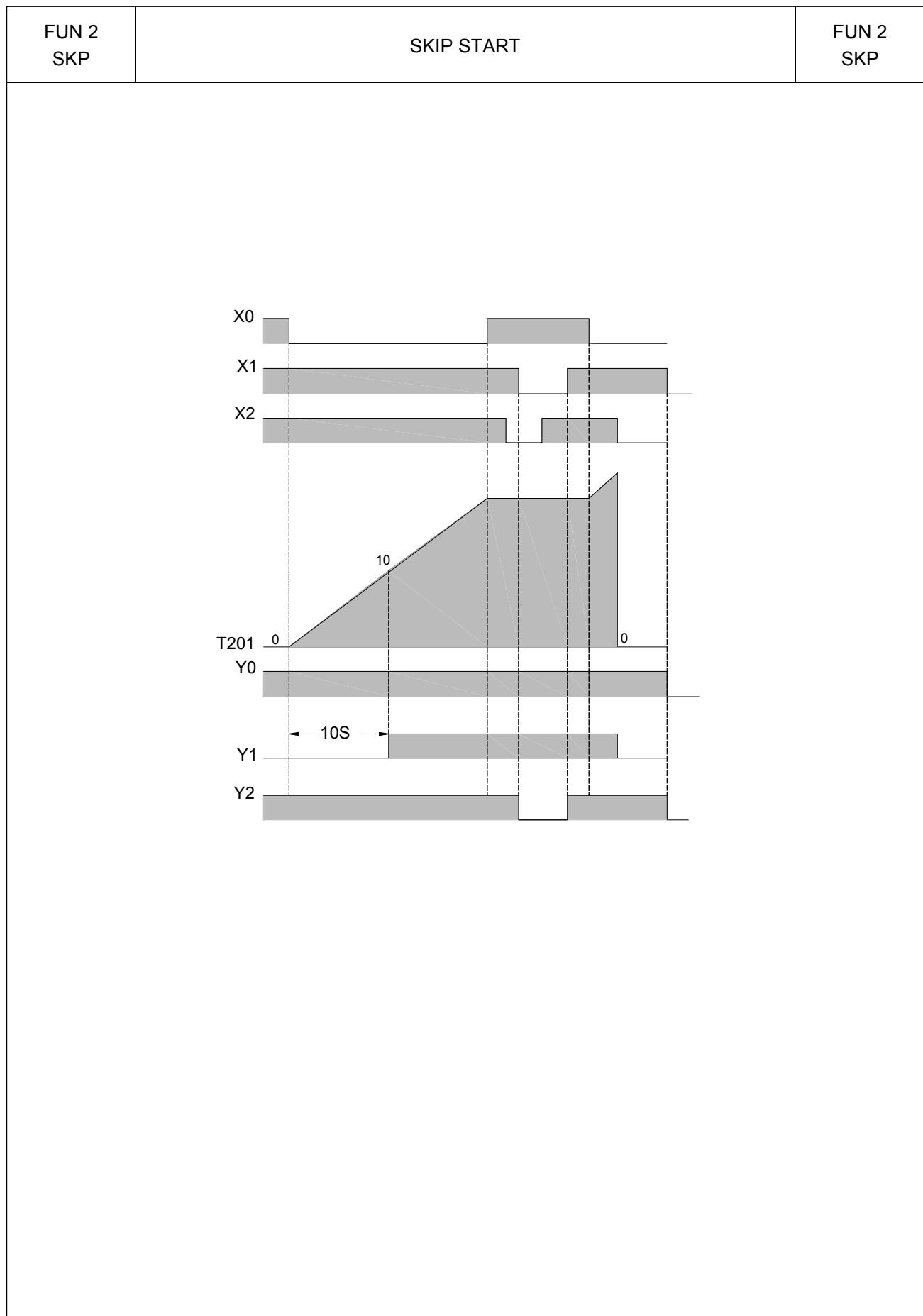


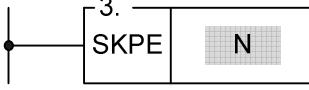
Basic Function Instruction

FUN 1 MCE	MASTER CONTROL LOOP END	FUN 1 MCE
Symbol		<u>Operand</u>
	 <p><u>Ladder symbol</u></p> <p>1.</p> <p>MCE N</p>	N: Master Control End number (N=0~127) N can not be used repeatedly.
Description		<ul style="list-style-type: none"> ● Every MCE N must correspond to a Master Control Start instruction. They must always be used as a pair and you should also make sure that the MCE N instruction is after the MC N instruction. After the MC N instruction has been executed, all output coil status and timers will be cleared to 0 and no other instructions will be executed. The program execution will resume until a MCE instruction which has the same N number as MC N instruction appears. ● MCE instruction does not require an input control because the instruction itself forms a network which other instructions can not connect to it. If the MC instruction has been executed then the master control operation will be completed when the execution of the program reaches the MCE instruction. If MC N instruction has never been executed then the MCE instruction will do nothing.
Description		<ul style="list-style-type: none"> ● Please refer to the example and explanations for MC instruction.

FUN 2 SKP	SKIP START	FUN 2 SKP																																													
Symbol																																															
	<u>Ladder symbol</u> Skip control— EN — 2. 	<u>Operand</u> N: Skip loop number (N=0~127), N can not be used repeatedly.																																													
Description																																															
	<ul style="list-style-type: none"> ● There are total 128 SKP loops (N=0~127). Every skip start instruction, SKP N, must correspond to a skip end instruction, SKPE N, which has the same loop number as SKP N. They must always be used as a pair and you should also make sure that the SKPE N instruction is after the SKP N instruction. ● When the skip control "EN" is 0, then the Skip Start instruction will not be executed. ● When the skip control "EN" is 1, the range between the SKP N and SKPE N which is so called the Skip active loop area will be skipped, that is all the instructions in this area will not be executed. Therefore the statuses of the discrete or registers in this Skip active loop area will be retained. 																																														
Example																																															
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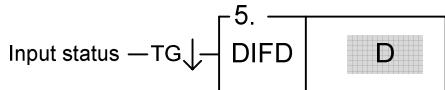
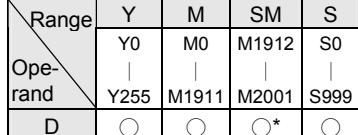
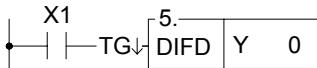
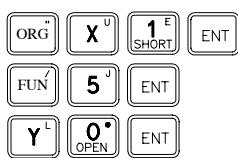
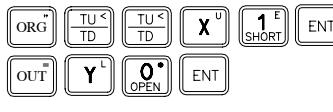
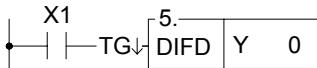
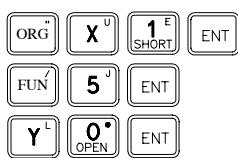
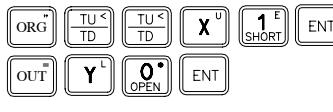
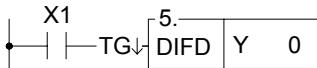
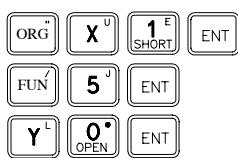
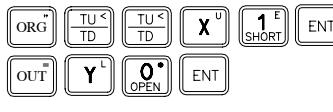
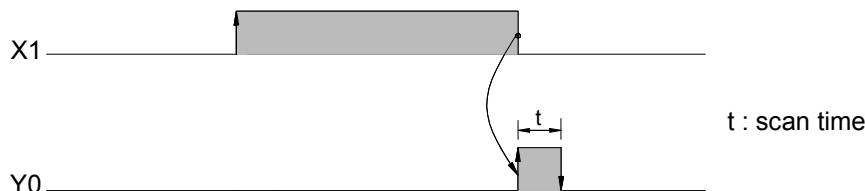
Basic Function Instruction



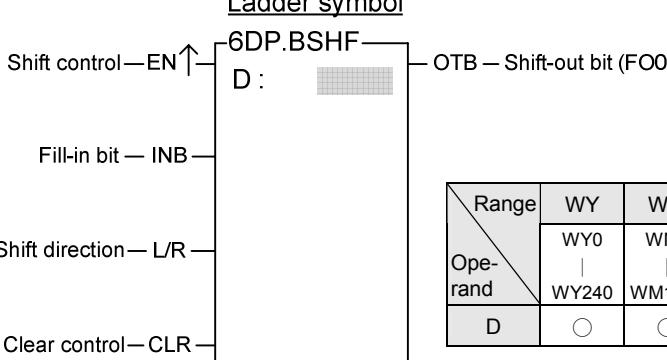
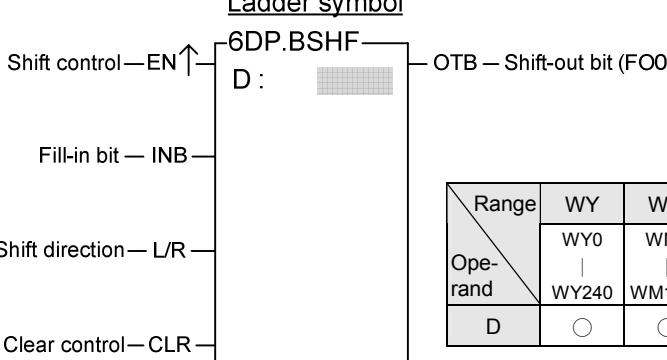
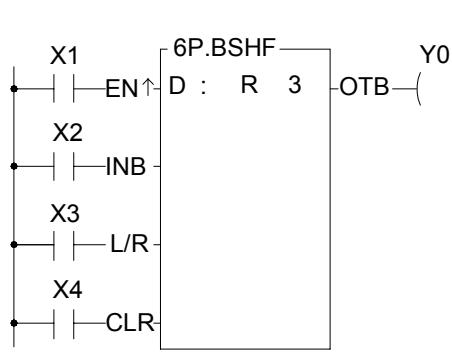
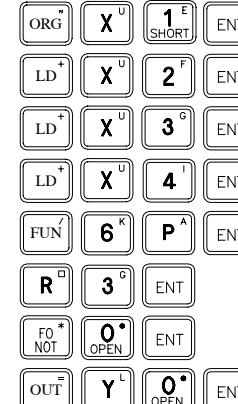
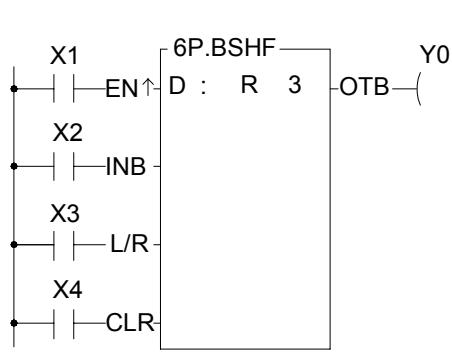
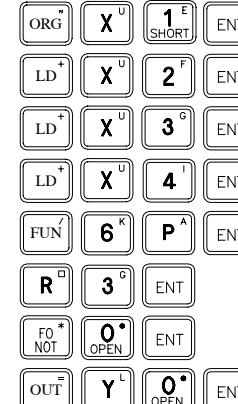
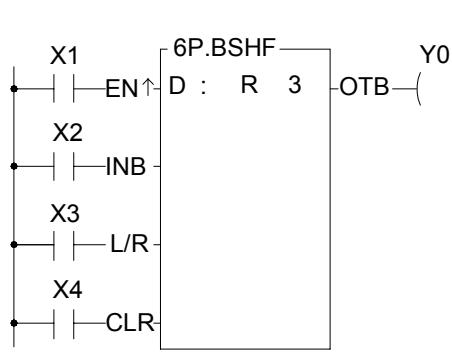
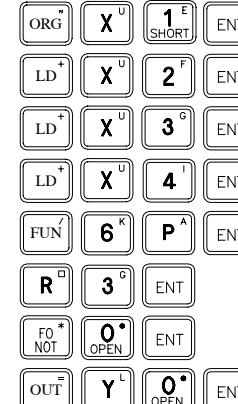
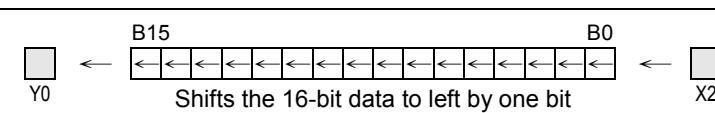
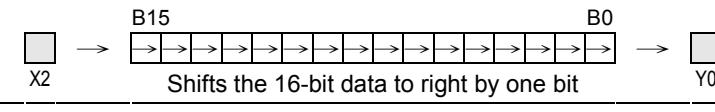
FUN 3 SKPE	SKIP END	FUN 3 SKPE
Symbol		<u>Operand</u>
	<u>Ladder symbol</u> 	N : SKIP END Loop number (N=0~127) N can not be used repeatedly.
Description		<ul style="list-style-type: none"> ● Every SKPE N must correspond to a SKP N instruction. They must always be used as a pair and you should also make sure that the SKPE N instruction is behind the SKP N instruction. ● SKPE instruction does not require an input control because the instruction itself forms a network which other instructions can not connect to it. If the SKP N instruction has been executed then the skip operation will be completed when the execution of the program reaches the SKPE N instruction. If SKP N instruction has never been executed then the SKPE instruction will do nothing.
Example		<ul style="list-style-type: none"> ● Please refer to the example and explanations for SKP N instruction. <p>Remark : SKP/SKPE instructions can be used by nesting or interleaving. The coding rules are the same as for the MC/MCE instructions. Please refer to the section of MC/MCE instructions.</p>

Basic Function Instruction

FUN 4 DIFU	DIFFERENTIAL UP	FUN 4 DIFU															
Symbol		<u>Operand</u>															
	<u>Ladder symbol</u>																
	<p>Input status — TG↑</p>	<p>D: a specific coil number where the result of the Differential Up operation is stored.</p>															
		<table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th style="text-align: center;">Range</th> <th style="text-align: center;">Y</th> <th style="text-align: center;">M</th> <th style="text-align: center;">SM</th> <th style="text-align: center;">S</th> </tr> </thead> <tbody> <tr> <td style="text-align: center;">Oper- and</td> <td style="text-align: center;">Y0 Y255</td> <td style="text-align: center;">M0 M1911</td> <td style="text-align: center;">M1912 M2001</td> <td style="text-align: center;">S0 S999</td> </tr> <tr> <td style="text-align: center;">D</td> <td style="text-align: center;">○</td> <td style="text-align: center;">○</td> <td style="text-align: center;">○*</td> <td style="text-align: center;">○</td> </tr> </tbody> </table>	Range	Y	M	SM	S	Oper- and	Y0 Y255	M0 M1911	M1912 M2001	S0 S999	D	○	○	○*	○
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Oper- and	Y0 Y255	M0 M1911	M1912 M2001	S0 S999													
D	○	○	○*	○													
Description	<ul style="list-style-type: none"> The DIFU instruction is used to output the up differentiation of a node status (status input to "TG ↑") and the pulse signal resulting from the status change at the rising edge of the "TG ↑" for one scan time is stored to a coil specified by D. The functionality of this instruction can also be achieved by using a TU contact. 																
Example	The results of the following two samples are exactly the same																
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Ladder Diagram	Key Operations	Mnemonic Codes															
Example 1 		ORG X 1 FUN 4 D : Y 0															
Example 2 		ORG TU X 1 OUT Y 0															
		t : scan time															

FUN 5 DIFD	DIFFERENTIAL DOWN	FUN 5 DIFD									
Symbol	<u>Ladder symbol</u> 	<u>Operand</u> N: a specific coil number where the result of the Differential Down operation is stored.									
											
Description	<ul style="list-style-type: none"> The DIFD instruction is used to output the down differentiation of a node status (status input to "TG ↓") and the pulse signal resulting from the status change at the falling edge of the "TG ↓" for one scan time is stored to a coil specified by D. The functionality of this instruction can also be achieved by using a TD contact. 										
Example	The results of the following two samples are exactly the same										
<table border="1"> <thead> <tr> <th>Ladder Diagram</th> <th>Key Operations</th> <th>Mnemonic Codes</th> </tr> </thead> <tbody> <tr> <td>Example 1 </td> <td></td> <td>ORG X 1 FUN 5 D : Y 0</td> </tr> <tr> <td>Example 2 </td> <td></td> <td>ORG TD X 1 OUT Y 0</td> </tr> </tbody> </table>			Ladder Diagram	Key Operations	Mnemonic Codes	Example 1 		ORG X 1 FUN 5 D : Y 0	Example 2 		ORG TD X 1 OUT Y 0
Ladder Diagram	Key Operations	Mnemonic Codes									
Example 1 		ORG X 1 FUN 5 D : Y 0									
Example 2 		ORG TD X 1 OUT Y 0									
 <p>t : scan time</p>											

Basic Function Instruction

FUN 6 DP BSHF	BIT SHIFT (Shifts the data of the 16-bit or 32-bit register to left or to right by one bit)	FUN 6 DP BSHF																																			
Symbol																																					
Ladder symbol 		<u>Operand</u> D: The register number for shifting																																			
		<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Range</th> <th>WY</th> <th>WM</th> <th>WS</th> <th>TMR</th> <th>CTR</th> <th>HR</th> <th>OR</th> <th>SR</th> <th>ROR</th> <th>DR</th> </tr> </thead> <tbody> <tr> <td style="text-align: left;">Operand</td> <td>WY0 WY240</td> <td>WM0 WM1896</td> <td>WS0 WS984</td> <td>T0 T255</td> <td>C0 C255</td> <td>R0 R3839</td> <td>R3904 R3967</td> <td>R3968 R4167</td> <td>R5000 R8071</td> <td>D0 D4095</td> </tr> <tr> <td style="text-align: left;">D</td> <td>○</td> <td>○</td> <td>○</td> <td>○</td> <td>○</td> <td>○</td> <td>○</td> <td>○*</td> <td>○*</td> <td>○</td> </tr> </tbody> </table>	Range	WY	WM	WS	TMR	CTR	HR	OR	SR	ROR	DR	Operand	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3904 R3967	R3968 R4167	R5000 R8071	D0 D4095	D	○	○	○	○	○	○	○	○*	○*	○		
Range	WY	WM	WS	TMR	CTR	HR	OR	SR	ROR	DR																											
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D	○	○	○	○	○	○	○	○*	○*	○																											
Description	<ul style="list-style-type: none"> ● When the status of clear control "CLR" is at 1, then the data of register D and FO0 will all be cleared to 0. Other input signals are all in effect. ● When the status of clear control is "CLR" at 0, then the shift operation is permissible. When the shift control "EN" = 1 or "EN ↑" (P instruction) from 0 to 1, the data of the register will be shifted to right (L/R=0) or to left (L/R=1) by one bit. The shifted-out bit (MSB when shift to left and LSB when shift to right) for both cases will be sent to FO0. The vacated bit space (LSB when shift to left and MSB when shift to right) due to shift operation will be filled in by the input status of fill-in bit "INB". 																																				
Example	Shifts the 16-bit register data																																				
<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: center;">Ladder diagram</th> <th style="text-align: center;">Key Operations</th> <th style="text-align: center;">Mnemonic Codes</th> </tr> </thead> <tbody> <tr> <td style="text-align: center;">  </td><td style="text-align: center;">  </td><td style="text-align: center;"> ORG X 1 LD X 2 LD X 3 LD X 4 FUN 6P D : R 3 FO 0 OUT Y 0 </td></tr> </tbody> </table>		Ladder diagram	Key Operations	Mnemonic Codes			ORG X 1 LD X 2 LD X 3 LD X 4 FUN 6P D : R 3 FO 0 OUT Y 0																														
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		ORG X 1 LD X 2 LD X 3 LD X 4 FUN 6P D : R 3 FO 0 OUT Y 0																																			
X3=1 (Left shift)	 <p>Shifts the 16-bit data to left by one bit</p>	B15 ← [←←←←←←←←←←←←←←←←←←←←←←] ← X2																																			
X3=0 (Right shift)	 <p>Shifts the 16-bit data to right by one bit</p>	X2 → [→→→→→→→→→→→→→→→→→→→→] → Y0																																			

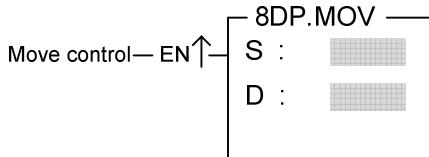
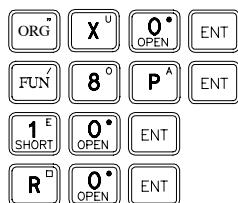
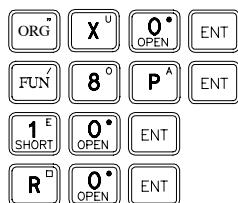
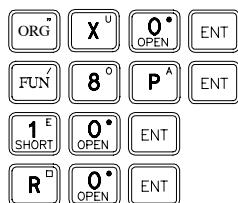
Symbol	Ladder symbol	Operand																																																								
		<u>CV</u> : The number of the Up/Down Counter <u>PV</u> : Preset value of the counter or it's register number																																																								
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PV	○	○	○	○	○	○	○	○	○	○	○	○	○																																													
Description		<ul style="list-style-type: none"> When the clear control "CLR" is 1, the counter's CV will be reset to 0 and the counter will not be able to count. When the clear control "CLR" is 0, counting will then be allowed. The nature of the instruction is a P instruction. Therefore, when the clock "CK↑" is 0→1 (rising edge), the CV will increase by 1 (if U/D=1) or decrease by 1 (if U/D=0). When CV=PV, FO0("Count-Up") will change to 1". If there are more clocks input, the counter will continue counting which cause CV≠PV. Then, FO0 will immediately change to 0. This means the "Count-Up" signal will only be equal to 1 if CV=PV, or else it will be equal to 0 (Care should be taken to this difference from the "Count-Up" signal of the general counter). The upper limit of up count value is 32767 (16-bit) or 2147483647 (32-bit). After the upper limit is reached, if another up count clock is received, the counting value will become -32768 or -2147483648 (the lower limit of down count). The lower limit of down count value is -32767 (16-bit) or -2147483647 (32-bit). After the lower limit is reached, if another down count clock is received, the counting value will become 32768 or 2147483648 (the upper limit of up count). If U/D is fixed as 1, the instruction will become a single-phase up count counter. If U/D is fixed as 0, the instruction will become a single-phase down count counter. 																																																								
Example	The diagram below is an application example of UDCTR instruction being applied to an encoder.																																																									

Basic Function Instruction

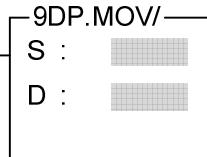
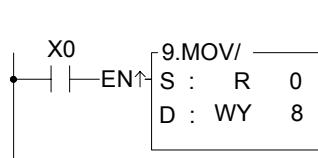
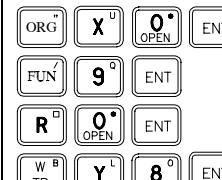
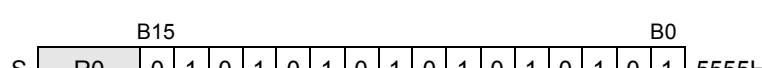
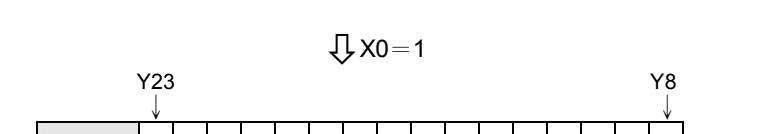
FUN 7 D UDCTR	UP/DOWN COUNTER (16-bit or 32-bit up/down 2-phase Counter)	FUN 7 D UDCTR						
		<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="background-color: #e0e0e0; padding: 5px;">Ladder Diagram</th><th style="background-color: #e0e0e0; padding: 5px;">Key Operations</th><th style="background-color: #e0e0e0; padding: 5px;">Mnemonic Codes</th></tr> </thead> <tbody> <tr> <td style="padding: 10px;"> </td><td style="padding: 10px;"> </td><td style="padding: 10px;"> ORG X 18 LD X 17 LD X 16 FUN 7 CV : R 0 PV : - 3 FO 0 OUT Y 0 </td></tr> </tbody> </table>	Ladder Diagram	Key Operations	Mnemonic Codes			ORG X 18 LD X 17 LD X 16 FUN 7 CV : R 0 PV : - 3 FO 0 OUT Y 0
Ladder Diagram	Key Operations	Mnemonic Codes						
		ORG X 18 LD X 17 LD X 16 FUN 7 CV : R 0 PV : - 3 FO 0 OUT Y 0						

Remark 1: Since the counting operation of UDCTR is implemented by software scanning, therefore if the clock speed is faster than the scan speed, lose count may then happen (generally the clock should not exceed 20Hz depending on the size of the program). Please use the software or hardware high-speed counter in the PLC. Refer to the "High Speed Counter Application" in the Advanced Manual.

Remark 2: In order to ensure the proper counting, the sustain time of the status of clock input should greater than 1 scan time.

FUN 8 DP MOV	MOVE (Moves data from S to D)	FUN 8 DP MOV																																																												
Description	<p><u>Ladder symbol</u></p>  <p><u>Operand</u></p> <p>S: Source register number D: Destination register number The S, N, D may combine with V, Z, P0~P9 to serve indirect addressing</p>																																																													
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D		○	○	○	○	○	○		○	○*	○*	○		○																																																
Description	<ul style="list-style-type: none"> Move (write) the data of S to a specified register D when the move control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. 																																																													
Example	Writes a constant data into a 16-bit register.																																																													
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		ORG X 0 FUN 8P S : 10 D : R 0																																																												
<p style="text-align: center;">S <input type="text" value="K"/> <input type="text" value="10"/></p> <p style="text-align: center;">$\downarrow X_0 = \text{↑}$</p> <p style="text-align: center;">D <input type="text" value="R0"/> <input type="text" value="10"/></p>																																																														

Basic Function Instruction

FUN 9 DP MOV/	MOVE INVERSE (Inverts the data of S and moves the result to a specified device D)												FUN 9 DP MOV/	
Symbol	<u>Ladder symbol</u> 												<u>Operand</u>	
	S: Source register number D: Destination register number S, N, D may combine with V, Z, P0~P9 to serve indirect addressing													
Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	SR	ROR	DR	K	XR
Oper- and	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3840 R3847	R3904 R3967	R3968 R4167	R5000 R8071	D0 D4095	16/32-bit +/- number	V · Z P0~P9
S	○	○	○	○	○	○	○	○	○	○	○	○	○	○
D		○	○	○	○	○	○		○	○*	○*	○		○
Description	<ul style="list-style-type: none"> Inverts the data of S (changes the status from 0 to 1 and from 1 to 0) and moves the results to a specified register D when the move control input "EN" =1 or "EN ↑" (P instruction) from 0 to1. 													
Example	Moves the inverted data of a 16-bit register to another 16-bit register.													
Ladder Diagram				Key Operations				Mnemonic Codes						
								ORG X 0 FUN 9 S : R 0 D : WY 8						
								X0 = 1						

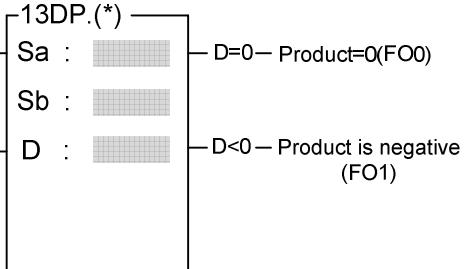
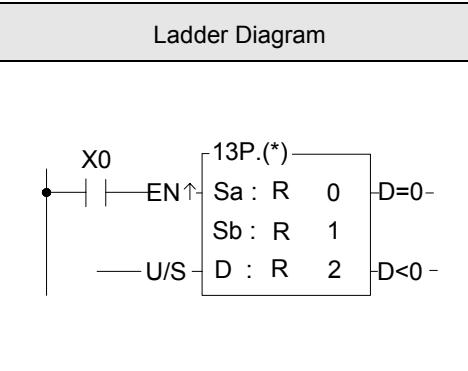
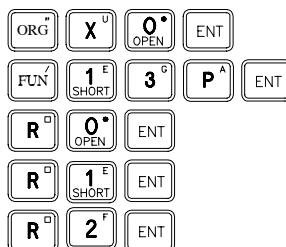
FUN 10 TOGG	TOGGLE SWITCH (Changes the output status when the rising edge of control input occur)	FUN 10 TOGG															
Symbol	<u>Ladder symbol</u> Input trigger — EN ↑ [10.] TOGG D	<u>Operand</u> D: the coil number of the toggle switch															
		<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>Range</th><th>Y</th><th>M</th><th>SM</th><th>S</th></tr> <tr> <td>Oper- and</td><td>Y0 Y255</td><td>M0 M1911</td><td>M1912 M2001</td><td>S0 S999</td></tr> <tr> <td>D</td><td>○</td><td>○</td><td>○*</td><td>○</td></tr> </table>	Range	Y	M	SM	S	Oper- and	Y0 Y255	M0 M1911	M1912 M2001	S0 S999	D	○	○	○*	○
Range	Y	M	SM	S													
Oper- and	Y0 Y255	M0 M1911	M1912 M2001	S0 S999													
D	○	○	○*	○													
Description	<ul style="list-style-type: none"> The coil D changes its status (from 1 to 0 and from 0 to 1) each time the input "TG ↑" is triggered from 0 to 1 (rising edge). 																
Example	<p>Ladder Diagram</p> <pre> X0 ---+--> TG↑ 10. TOGG Y 0 +-----+ </pre>	<p>Key Operations</p> <pre> ORG X 0 FUN 10 D : Y 0 </pre>															

Basic Function Instruction

FUN 11 DP (+)	ADDITION (Performs addition of the data specified at Sa and Sb and stores the result in D)	FUN 11 DP (+)																																																																								
Symbol																																																																										
	<u>Ladder symbol</u>	<u>Operand</u>																																																																								
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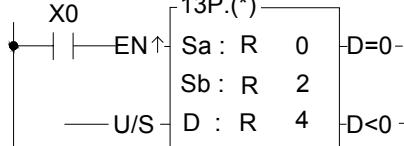
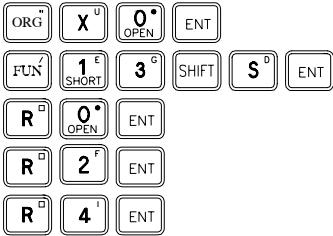
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Basic Function Instruction

FUN 13 DP (*)	MULTIPLICATION (Performs multiplication of the data specified at Sa and Sb and stores the result in D)	FUN 13 DP (*)																																																																											
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Basic Function Instruction

FUN 13 DP (*)	MULTIPLICATION (Performs multiplication of the data specified at Sa and Sb and stores the result in D)	FUN 13 DP (*)
Example 2	32-bit multiplication	

Ladder Diagram	Key Operations	Mnemonic Codes			
		ORG X 0 FUN 13D <table style="margin-left: auto; margin-right: auto;"> <tr> <td>Sa : R 0</td> </tr> <tr> <td>Sb : R 2</td> </tr> <tr> <td>D : R 4</td> </tr> </table>	Sa : R 0	Sb : R 2	D : R 4
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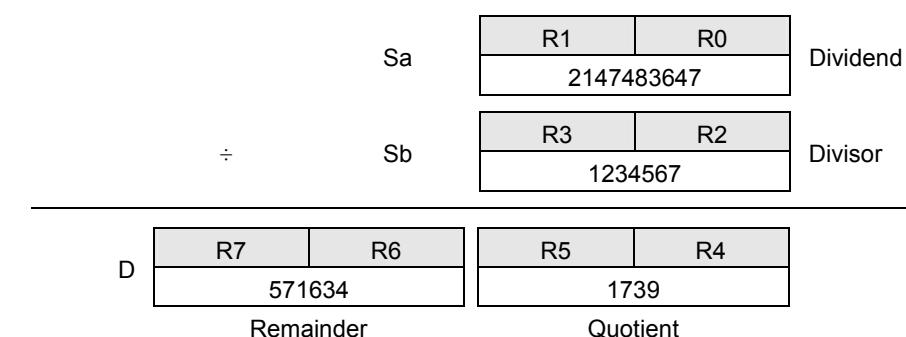


Basic Function Instruction

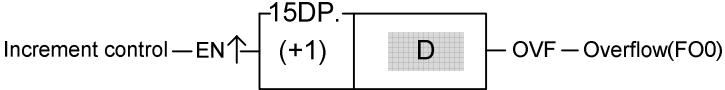
FUN 14 DP (/)	DIVISION (Performs division of the data specified at Sa and Sb and stores the result in D)	FUN 14 DP (/)																																																																								
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FUN 14 DP (/)	DIVISION (Performs division of the data specified at Sa and Sb and stores the result in D)	FUN 14 DP (/)
Example 2	32-bit division	

Ladder Diagram	Key Operations	Mnemonic Codes
		ORG X 0 FUN 14D Sa : R 0 Sb : R 2 D : R 4

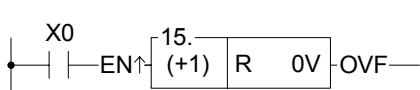


Basic Function Instruction

FUN 15 D P (+1)	INCREMENT (Adds 1 to the D value)	FUN 15 D P (+1)
<u>Ladder symbol</u> 	<u>Operand</u> <p>D : The register to be increased D may combine with V, Z, P0~P9 to serve indirect addressing</p>	

Range	WY	WM	WS	TMR	CTR	HR	OR	HR	HSCR	RTC	SR	ROR	DR	XR
Oper- and	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3904 R3919	R3920 R4047	R4096 R4127	R4128 R4135	R4136 R4167	R5000 R8071	D0 D4095	V、Z P0~P9
	D	○	○	○	○	○	○	○	○	○	○*	○*	○	○

- Adds 1 to the register D when the increment control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. If the value of D is already at the upper limit of positive number 32767 or 2147483647, adding one to this value will change it to the lower limit of negative number -32768 or -2147483648. At the same time, the overflow flag FO0 (OVF) is set to 1.

Example	16-bit increment register	
	Key operations 	Mnemonic code <pre>ORG TU X 0 FUN 15 D : R 0V</pre>

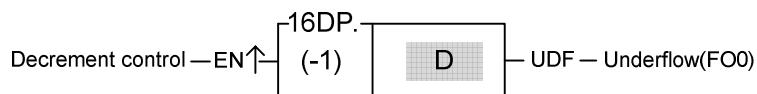
When V=100, 0 + 100 = 100

D [R100 | 1]

↓ X0 = ↗

D [R100 | 2]

FUN 16 D P (-1)	DECREMENT (Subtracts 1 from the D value)	FUN 16 D P (-1)
--------------------	---	--------------------

Ladder symbolOperand

D : The register to be decreased
D may combine with V, Z, P0~P9 to serve indirect addressing

Range	WY	WM	WS	TMR	CTR	HR	OR	HR	HSCR	RTCR	SR	ROR	DR	XR
Oper- and	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3904 R3919	R3920 R4047	R4096 R4127	R4128 R4135	R4136 R4167	R5000 R8071	D0 D4095	V、Z P0~P9
D	○	○	○	○	○	○	○	○	○	○	○*	○*	○	○

Description

- Subtracts 1 from the register D when the decrement control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. If the value of D is already at the lower limit of negative number -32768 or -2147483648, subtracting one from this value will change it to the upper limit of positive number 32767 or 2147483647. At the same time, the underflow flag FO0 (UDF) is set to 1.

Example

16-bit decrement register

Ladder diagram	Key operations	Mnemonic code
		ORG X 0 FUN 16P D : R 0

D [R0] 0

↓ X0 = ↓

D [R0] -1

Basic Function Instruction

FUN 17 D P CMP	COMPARE (Compares the data of Sa and Sb and outputs the results to function Outputs)	FUN 17 D P CMP																																																																	
<u>Ladder symbol</u>		<u>Operand</u>																																																																	
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<ul style="list-style-type: none"> ● Compares the data of Sa and Sb when the compare control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. If the data of Sa is equal to Sb, then set FO0 to 1. If the data of Sa>Sb, then set FO1 to 1. If the data of Sa<Sb, then set FO2 to 1. If the data of Sa < Sb, then set the FO2 to 1. 																																																																			
Example	Compares the data of 16-bit register																																																																		
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<ul style="list-style-type: none"> ● From the above example, we first assume the data of R0 is 1 and R1 is 2, and then compare the data by executing the CMP instruction. The FO0 and FO1 are set to 0 and FO2 (a<b) is set to 1 since a<b. ● If you want to have the compound results, such as \geq , \leq , $<$, $>$ etc., please send = , \leq , $<$ and $>$ results to relay first and then combine the result from the relays. ● M1919=0, when this command is not executed, FO0, FO1, FO2 will remain in the status at last execution. ● M1919=1, when this command is not executed, FO0, FO1, FO2 are all cleared to 0. ● Control M1919 properly to obtain memory-holding function for functional command output. 																																																																			

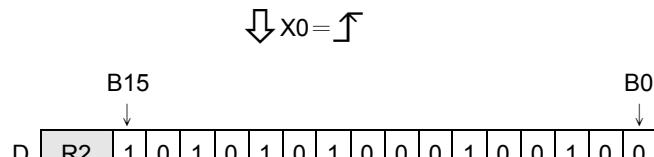
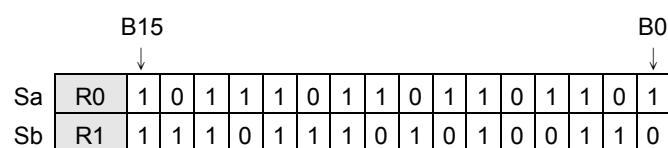
FUN 18 AND	LOGICAL AND	FUN 18 AND
<u>Ladder symbol</u>  <p>Operation control— EN ↑</p> <p>18DP.AND</p> <p>Sa : </p> <p>Sb : </p> <p>D : </p> <p>D=0—Result is 0 (FO0)</p>	<u>Operand</u> <p>Sa: The register to be ANDed</p> <p>Sb: The register to be ANDed</p> <p>D : The register to store the result of AND</p> <p>The Sa, Sb, D may combine with V, Z, P0~P9 to serve indirect addressing application</p>	

Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	HR	HSCR	RTCR	SR	ROR	DR	K
Oper- and	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3804 R3903	R3904 R3919	R3920 R4047	R4096 R4127	R4128 R4135	R4136 R4167	R5000 R8071	D0 D4095	16/32 bit +/-number
	Sa	○	○	○	○	○	○	○	○	○	○	○	○	○	○	
	Sb	○	○	○	○	○	○	○	○	○	○	○	○	○	○	
D		○	○	○	○	○	○		○	○	○	○	○*	○*	○	

- Performs logical AND operation for the data of Sa and Sb when the operation control input "EN" =1 or "EN ↑ " (P instruction) from 0 to 1. This operation compares the corresponding bits of Sa and Sb (B0~B15 or B0~B31). The bit in the D is set to 1 if both of the corresponding bits data of Sa and Sb is 1. The bit in the D is set to 0 if one of the corresponding bits is 0.

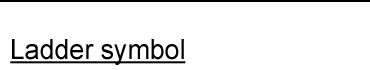
Example Operation of 16-bit logical AND

Ladder diagram	Key operations	Mnemonic code
<p>X0 EN ↑ 18P.AND Sa : R 0 Sb : R 1 D : R 2</p>		ORG X 0 FUN 18P Sa : R 0 Sb : R 1 D : R 2



Basic Function Instruction

FUN 19 D P OR	LOGICAL OR	FUN 19 D P OR																																																																																																			
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<p>Operation control—EN ↑</p> <p>19.DP.OR</p> <p>Sa : R 0</p> <p>Sb : R 1</p> <p>D : R 2</p> <p>D=0—Result is 0 (FO0)</p>		<u>Operand</u>																																																																																																			
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<ul style="list-style-type: none"> ● Performs logical OR operation for the data of Sa and Sb when the operation control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. This operation compares the corresponding bits of Sa and Sb (B0~B15 or B0~B31). The bit in the D is set to 1 if one of the corresponding bits of Sa or Sb is 1. The bit in the D is set to 0 if both of the corresponding bits of Sa and Sb is 0. 																																																																																																					
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FUN 20 D P \rightarrow BCD	BIN TO BCD CONVERSION (Converts BIN data of the device specified at S into BCD and stores the result in D)	FUN 20 D P \rightarrow BCD
	 <p><u>Ladder symbol</u></p> <p>Conversion control—EN↑</p> <p>20DP. → BCD</p> <p>S : [] — ERR—Error (FO0)</p> <p>D : []</p>	<u>Operand</u> <p>S : The register to be converted</p> <p>D : The register to store the converted data (BCD code)</p> <p>The S, D may combine with V, Z, P0~P9 to serve indirect addressing</p>

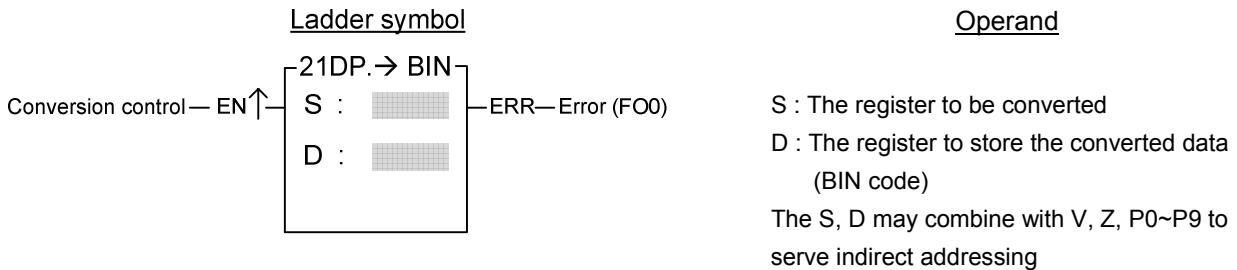
Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	HR	HSCR	RTCR	SR	ROR	DR	K
Operand	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T0 T255	C0 C255	R0 R3839	R3804 R3903	R3940 R3919	R3920 R4047	R4096 R4127	R4128 R4135	R4136 R4167	R5000 R8071	D0 D4095	16/32 bit +/- number
	S	D														
	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
		○	○	○	○	○	○		○	○	○	○	○*	○*	○	

- FB-PLC uses binary code to store and to execute calculations. If want to send the internal PLC data to the external displays such as seven-segment displays, it is more convenient for us to read the result on screen by converting the BIN data to BCD data. For example, it is more clear for us to read the reading "12" instead of the binary code "1100."
 - Converts BIN data of the device specified at S into BCD and writes the result in D when the operation control input "EN" =1 or "EN ↑" ( instruction) from 0 to 1. If the data in S is not a BCD value (0~9999 or 0~9999999), then the error flag F00 is set to 1 and the old data of D are retained.

Example	16-bit BIN to BCD conversion	
Ladder diagram	Key operations	Mnemonic code
		ORG X 0 FUN 20 S : 9999 D : R 0

Basic Function Instruction

FUN 21 D P →BIN	BCD TO BIN CONVERSION (Converts BCD data of the device specified at S into BIN and stores the result in D)	FUN 21 D P →BIN
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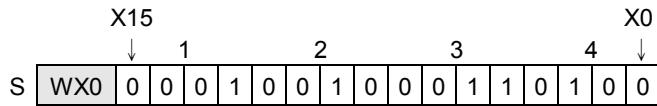


Range	WX	WY	WM	WS	TMR	CTR	HR	IR	OR	HR	HSCR	RTCR	SR	ROR	DR
	WX0 WX240	WY0 WY240	WM0 WM1896	WS0 WS984	T255	C0 C255	R0 R3839	R3840 R3903	R3904 R3919	R3920 R4047	R4096 R4127	R4128 R4135	R4136 R4167	R5000 R8071	D0 D4095
S	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
D		○	○	○	○	○	○		○	○	○	○	○*	○*	○

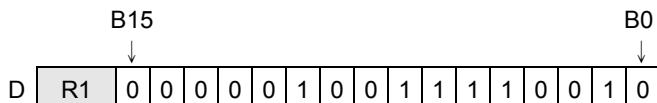
- The decimal (BCD) data must be converted to binary (BIN) data first in order for PLC to accept the data which is originally in decimal unit (BCD code) inputted from external device such as digital switch because the BCD data can not be accepted by PLC for its operations.
- Converts BCD data of the device specified at S into BIN and writes the result in D when the operation control input "EN" =1 or "EN ↑" (P instruction) from 0 to 1. If the data in S is not in BCD, then the error flag FO0 is set to 1 and the old data of D are retained.
- Constant is converted to BIN automatically when store in program and can not be used as a source operand of this function.

Example	16-bit BCD to BIN conversion	
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Ladder diagram	Key operations	Mnemonic code
		<p>ORG X 0 FUN 21P S : WX 0 D : R 1</p>



$$\Downarrow x_0 = \boxed{1}$$



B0
↓